Lecture - 3: Planetary Motion Workshop on Mechanics and Python

Vikram Vyas

The Ajit Foundation, Bikaner

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References

This lecture is based on Chapter 9 of The Feynman Lectures in Physics, Volume 1

A Three Dimensional Coordinate System

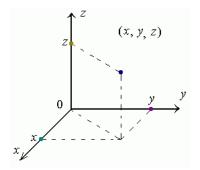


Figure: Three Dimensional Cartesian Coordinate System

Motion in Three Dimensions

Motion of a particle in a cartesian coordinate system

We have to make a table of three entries, giving the position of the particle in three dimensions

x = x(t)y = y(t)z = z(t)

t	X	y	Ζ
0	1.0	0.0	0.0
0.1	2.0	0.1	0.5
0.2	2.9	0.7	1.4

Figure: An example of a motion in three dimension

Motion in Three Dimensions: Graph

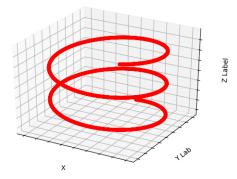


Figure: Motion of a particle in three dimensions

Velocity in Three Dimensions:

Velocity in three dimensional cartesian coordinate system

$$v_{x}(t) = \lim_{\Delta t \to 0} \frac{x(t + \Delta t) - x(t)}{\Delta t} \equiv \frac{dx}{dt}$$
$$v_{y}(t) = \lim_{\Delta t \to 0} \frac{y(t + \Delta t) - y(t)}{\Delta t} \equiv \frac{dy}{dt}$$
$$v_{z}(t) = \lim_{\Delta t \to 0} \frac{z(t + \Delta t) - z(t)}{\Delta t} \equiv \frac{dz}{dt}$$

Acceleration in Three Dimensions

Acceleration in three dimensional cartesian coordinate system

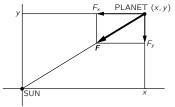
$$a_{x}(t) = \lim_{\Delta t \to 0} \frac{v_{x}(t + \Delta t) - v_{x}(t)}{\Delta t} \equiv \frac{dv_{x}}{dt} = \frac{d^{2}x}{dt^{2}}$$
$$a_{y}(t) = \lim_{\Delta t \to 0} \frac{v_{y}(t + \Delta t) - v_{y}(t)}{\Delta t} \equiv \frac{dv_{y}}{dt} = \frac{d^{2}y}{dt^{2}}$$
$$a_{z}(t) = \lim_{\Delta t \to 0} \frac{v_{z}(t + \Delta t) - v_{z}(t)}{\Delta t} \equiv \frac{dv_{z}}{dt} = \frac{d^{2}z}{dt^{2}}$$

Newton's Laws in Three Dimensions

Newton's laws of motion for a particle in three dimensional cartesian coordinate system

$$F_{x} = \frac{d}{dt} (mv_{x}) = ma_{x}$$
$$F_{y} = \frac{d}{dt} (mv_{y}) = ma_{y}$$
$$F_{z} = \frac{d}{dt} (mv_{z}) = ma_{z}$$

Gravitational Force



Force on a planet due to the Sun The motion is confined to a plane

$$ma_{x} = -GM_{g}m_{g}\frac{x}{r^{3}}$$

$$ma_{y} = -GM_{g}m_{g}\frac{y}{r^{3}}$$

$$r = \sqrt{x^{2} + y^{2}}$$

Where *m* is the inertial mass of the particle while m_g and M_g are the gravitational mass of the particle and the Sun.

Principle of Equivalence

A fundamental property of the gravitational force

The gravitational mass of the particle is same as its inertial mass

 $m_g = m$

Motion of Earth around the Sun

The one body problem

We will consider the case when M >> m and we can neglect the motion of the Sun. Then in the rest frame of the Sun the motion of Earth is governed by the following equations

$$a_{x} = -GM\frac{x}{r}$$

$$a_{y} = -GM\frac{y}{r^{3}}$$

$$r = \sqrt{x^{2} + y^{2}},$$

together with four initial conditions

$$x(0) = x_0;$$
 $v_x(0) = v_{x0}$
 $y(0) = y_0;$ $v_y(0) = v_{y0}.$